

Intelligent water pump frequency converter
A simple manual

Safety Information and precautions

- 1、The wiring must be done by qualified professional electrical engineers, otherwise it may cause electric shock or damage to the inverter.
- 2、Connect the wire when the power supply is disconnected, otherwise it may cause electric shock or fire.
- 3、Ground terminal⊕It is necessary to be reliably grounded, otherwise the inverter housing is dangerous to be electrified (board and shell silk screen).
- 4、Do not touch the main circuit terminal, and do not contact the main circuit terminal wiring of the inverter with the shell, otherwise it may cause electric shock.
- 5、Do not use circuit breaker to control the stop and start of the inverter, otherwise it may cause damage to the inverter.
- 6、The radiator is at a high temperature. Do not touch it, otherwise you may get burned.
- 7、The preset parameters of the frequency converter can meet the requirements of most equipment. If not necessary, do not modify the parameters of the frequency converter at will. Even if some equipment has special requirements, only the necessary parameters can be modified. Otherwise, random modification of parameters may cause damage to the equipment.
- 8、The company guarantees and repairs the product according to the Product Quality Management Law, and does not bear joint liability. If the motor is faulty or burned out after the user uses the product, the company does not take responsibility for the repair or compensation of the motor, and does not bear joint liability for the impact caused by the machine failure on the user.

Note: This parameter is not specifed in some functions of the simple manual. If necessary, please call our company for consultation on the complete manual

Operation panel description

1. Operation button description:
- (1) Menu: Use when switching from fixed mode to parameter mode.
- (2) Pressure/set: the shortcut key for setting water pressure and the key for determining parameters.
- (3) Shift: Shift the cursor when switching the display content and modifying parameters. Press the "Shift" key in the running state to change the running frequency, When switching back and forth between the output current, set pressure and feedback pressure, press the "shift" key to modify the parameter, and the flashing bit is the current modifiable bit.
- (4) Key: Used to set the parameter value and modify the set pressure value.
- (5) Operation: The start button is the start mode when the keyboard is used.
- (6) Stop: Stop button and fault reset button when the start mode is keyboard.
- 2、Indicator light description:
- Operation: (always on) operation indicator; (flashing) sleep shutdown indicator;
- Stop: shutdown indication (standby indication);
- Online: the network of multiple pumps is always on when it is successful, and does not light up when there is an error or no network;
- Alarm: frequency corverter protection alarm;
- Frequency: When it is always on, the value of the display screen represents the operating frequency;
- Current: when it is always on, it represents the value of the display screen as the operating current;
- Voltage: when it is always on, it represents the value of the display screen as the DC bus voltage;
- Set pressure: when the frequency and current lights are on at the same time, the value of the display screen represents the set pressure value;
- Feedback pressure: When the frequency and voltage lights are on at the same time, the value of the display screen represents the feedback

Step 1: Set the sensor range, sensor feedback type, sensor voltage, etc.:

P0.08=16.0 Sensor range

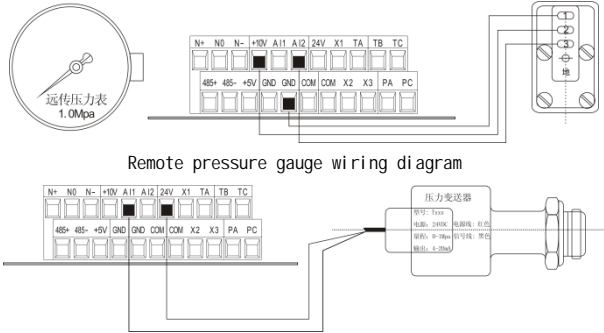
Step 2: Determine the pump direction:

A short trial run is used to observe whether the pump is turning in the right direction. The pump can be turned in the following two ways:

Disconnect the input power supply, and wait for the inverter to display off, then switch any two phases of the inverter output power line U, V, W;

Stop the inverter and modify the parameter P0.02

Sensor wiring method (Note: there is a short connection between COM and GND when the sensor leaves the factory)



Two-wire pressure transmitter wiring diagram

Macro parameter setting (multi-frequency converter online parameters)

Please refer to the P0.20 parameter table to debug the parameters of the main engine and auxiliary engine

System type	Main engine	1# auxl - liary machl ne	2# auxl - liary machl ne	3# auxl - liary machl ne	4# auxl - liary machl ne	5# auxl - liary machl ne
Single pump water supply Set up	P 0.20 =1	\	\	\	\	\
Two networks Host se-tup	P 0.20 =2	P0.20=11	\	\	\	\
Three units are networked Host se-tup	P 0.20 =3	P0.20=11	P0.20=12	\	\	\
Four un-its are networked Host se-tup	P 0.20 =4	P0.20=11	P0.20=12	P0.20=13	\	\
Five un-its net-work Host se-tup	P 0.20 =5	P0.20=11	P0.20=12	P0.20=13	P0.20=14	\
Six units are net-worked Host se-tup	P 0.20 =6	P0.20=11	P0.20=12	P0.20=13	P0.20=14	P0.20=15
One drag two water supply mode	P 0.20 =7	\	\	\	\	\
One drag and mul-tiple water supply mode	P 0.20 =8	\	\	\	\	\
Emergency water supply mode	P 0.20 =9	\	\	\	\	\

2. Common parameter group for a single machineCommon parameter group for multi-pump linkage

FC	Function code de-scription	Set the scope	Minimu m unit	Fact ory valu e	Ch an ge	Remarks
P 0.00	Pressure setting	P4.01~P0.10	0.1 Bar	3.0 Bar	○	When using multi-link, only the host pressure value needs to be set
P 0.01	Start	0.0 Bar~P0.00	0.1 Bar	2.4 Bar	○	Below the wake-up pres-sure value, wake up from sleep
P 0.02	Motor steering	0: Forward 1: Reversal	1	0	●	You can change this parameter Change the pump direction
P 0.03	Anti-freeze function	0: Off 1: Start, count in seconds 2: Turn it on and time it by minutes	1	0	○	The pump itself is frost-proof Rust function, please refer to P0.12-P0.14 for detailed Settings When there are multiple uni-ts, each changes The frequency converter sh-ould be set separately to prevent free-zing.
P 0.04	The leak is large Small coefficient	0.0s~100.0s	0.1s	5.0s	○	The bigger the leak, The smaller the coeffici-ent
P 0.05	Start/stop si-gnal se-lection	0: Start and stop the keyb-oard 1: Terminal start and stop 2: Communicat-ion control start and stop	1	0	○	When there are multiple uni-ts, lay the machine It must be set to 2
P 0.06	Autostart function	0~1	1	0	○	0: Off 1. Turn it on
P 0.07	The delay starts	0.0s~100.0s	0.1s	5.0s	○	The delay time before autom-atic start
P 0.08	Sensor range	0.0 Bar~200.0 Bar	0.1 Bar	16.0 Bar	○	Corresponding to the sensor Metre fullsc-ale
P 0.09	Sensor feedback Channel selection	0:AI1 1:AI2 2:Max (AI1, AI2) 3:Min (AI1, AI2)	1	2	○	AI1 defaults to power on Flow feedback; AI2 factory

FC	Envel op of func-tion	Set the de-scription	Minimu nity	Facto ry value	Ch an ge	Remarks
p 1.00	Multiple pumps in series Postal address	0~5	1	0	◎	1~5 is the address of the paver; The host add-ress is 0
P 1.01	Multi-split unit Backup host ac-tion se-lection	0: Shutdown 1: Constant speed 2: Constant pressure	1	0	○	0: The slave machine stops after the host is lost 1: The multi-link standby host can sel-ect constant speed operat-ion without connecting the sensor. 2: Sui table for the stan-dby host con-nected with sensors, The network operates at constant pre-ssure. (Assistance Settings)
p 1.02	Multi-link ne-twork mode se-lection	0: From the machine 1: Host	1	0	◎	0: CAN are used as multi-processor sl-aves. (The slave can only be set to 0) 1: CAN as a multi-link host.
P 1.03	Number of multi-link la-ying ma-chines	0~5	1	0	◎	When 0 is se-lected, the host cancels the control function to the slave. Note: This parameter only works when the PID frequency source is used and the CAN is the host.
P 1.04	Multi-achieve operation mode	0: Multi-pump main paving control 1: Multi-pump synchronous control 2: Control of multiple pu-mps with one in use and one in rese-rve	1	0	●	0: The control pressure of multiple pump main laying is insufficient The pump is put into ope-ration for the first time. 1: The press-ure of multi-pump synchro-nous control is insuffici-ent The pump runs at the same frequency. 2: Control any time with one pump for one use and one backup Only one pump is in operat-ion Ok, the rest of the pumps are in stand-by.

pressure value of the pipe network;

Pressure conversion relationship

0.1MPa (megapascal) = 100kPa (kilopascal) = 1bar (bar) = 1kgf/cm² (kgf/cm²)

Control terminal identification and description

Terminal symbol	Terminal name	Technical specifications
X1~X3	Multi functional digital input terminal Son	1. The optocoupler isolates the single input 2. When connected to COM, it is ON; when open circuit, it is OFF 3. Input voltage range: 9~36VDC 4. Input impedance: 4k
COM	Common port	Multi functional digital input common terminal
AI1	Analog input terminal 1	Default 4~20mA input, set to select 0~10V input, default impedance 500
AI2	Analog input terminal 2	The default input is 0~10V, and the setting can select 4~20mA input. The default impedance is 22k
24V	Simulate reference voltage	24V, ±5%, maximum output current 100mA
+10V	Simulate the reference voltage	10V, ±5%, maximum output current 50mA
+5V	Simulate the reference voltage	5V, ±5%, maximum output current 30mA
GND	Simulated ground end	To simulate the reference zero potential of the reference voltage
TA/TB/TC	Relay 1 output	TA-TB: normally closed terminal TA-TC: normally open terminal AC 250V/3A DC 30V/1A
PA/PC	Relay 2 output	PA-PC: Common starter AC 250V/3A DC 30V/1A
N+/N0/N-	CAN networking communication port	Standard CAN communication interface, when multi-connection control is used, please use twisted pair or shielded cable and connect N+, N0, N-
485+/485-	RS485 Upper computer Communication port	Standard RS485 Communication interface, please use twisted pair or shielded cable and connect

Quick debugging parameter setting

Follow the following steps to complete debugging

Pump frequency converter parameter table

Note: " " Indicates that the set value of this parameter can be changed in both standby and running states of the frequency converter.

" " Indicates that the set value of this parameter cannot be changed when the Inverter is in operation.

" " Indicates that the value of this parameter is the actual test record value and cannot be changed.

1. Status panel display parameters (Note: press the "Shift" key to switch display)

Show	Name	Explain	Unit	Remarks
P	Current pre-ssures	System real-time pressure	Bar	☉
H	Running frequency	Current running frequency	Hz	☉
d	Setting pre-ssure	The system sets the pressure	Bar	☉
A	Running current	Machine output current	A	☉
U	Busbar voltage	Machine bus voltage	V	☉

						default voltage feedback
P 0.10	High alarm Set value	P0.00~P0.08	0.1 Bar	12.8 Bar	○	The feedback pressure is greater than or equal to When the set value is set, the alarm will stop after a delay of 0.1 seconds. Normal pressure is restored Over reset delay time The fault is automatically removed after that
P 0.12	Anti-freeze operating frequency	0.00Hz~ upper limit frequency P2.07	0.01Hz	10.00 Hz	○	The time for anti-freezing and rust prevention The unit can be seconds, You can also divide it by referring to the setting of P0.03. The interval is set as 0 At this time, it is always operated at the freezing prevention frequency.
P 0.13	Freeze-proofing Performance period	0s/min~65000s/min	1s/min	60s/min	○	
P 0.14	Run in freezing conditions Interval	0s/min~65000s/min	1s/min	300s/min	○	
P 0.15	Frequency converter operating mode	0~1	1	0	○	0: Constant pressure control mode 1) General speed control mode
P 0.18	Acceleration time	0.0s~6500.0s	0.0s	5.0s	○	Distinguish by power segment
P 0.19	Deceleration time	0.0s~6500.0s	0.1s	5.0s	○	Distinguish by power segment
P 0.20	Multi-Linked Macro Debugging facility	0~15	1	0	●	

P 1.05	Multi-axial rotation interval time	0 min ~ 3600 min	1 min	120 min	○	The main mowers are rotated at regular intervals Set the interval time When it is 0, cancel the main Pump rotation function.
P 1.06	Address setting of multi-split small pump	1~6	1	6	○	When a small pump is needed, set the corresponding small pump address to this parameter, Set it to 1, and it will be number 1 The paver is a small pump; if so The value is greater than the auxiliary machine address, Then the function of the small pump is invalid.
P 1.07	Delay time for multi-split pump	0.0s ~ 100.0s	0.1s	5.0s	○	Insufficient online pressure Time, Delay in adding the pump Interim.
P 1.08	One drag two work mode	0: Fixed variable frequency pump 1: Alternating frequency pump	1	0	●	Set it to rotation mode At this time, the rotation time is set by P1.05 (using the one-to-two function, default end Start up) Please refer to the electronic version of the system electrical diagram for details
P 1.17	The standby host is started Command control	0: controlled by the original start signal of the standby host 1: Automatic start when powered on	1	1	○	When the standby host is enabled After that, it can be repaired Change this parameter and select The way to start the command
P 1.18	The communications are activated Command	0: Upper computer start control 1: Multi-	1	1	○	When the host is installed, it can be modified This parameter

	control	serial com- munication control				is selected as by The host di- rectly controls the start and stop of the machine
P 1.19	Start Coefficien t of pr- oportiona lity	50.0% ~ 95.0%	0.1%	90.0%	<input type="radio"/>	You can change this value Change the percentage of start-up pre- ssure deviat- ion

4、 Debug parameter group

FC	Function declarat ion	Set the scope	Minimu m unit	Facto ry value	Ch an ge	Remarks
P2.00	AI1 ch-annel feedback type selection	0:4-20mA 1:0-10V 2:0.5-4.5V 3:0-5V	1	0	○	AI1 is fact-ory default for current feedback 4-20 mA type
P2.02	AI2 ch-annel feedback type selection	0:4-20mA 1:0-10V 2:0.5-4.5V 3:3:0-5V	1	1	○	AI2 is fact-ory default for voltage feedback type 0-10V
P2.05	Freque ncy source selection	0: The digital setting up and down keys and pulse knob are adjusted (Drop power and do not rememb-er) 1: The digital setting is ad-justed by the up and down keys and the pulse knob (Drop memory) 2: AI1 3: AI2 5: Emergency water supply 8: PID 9: Communicat-ion given	1	8	●	Select 8 au-xiliary mac-hines, select 9 auxiliary machines, and select 1 em-ergency water supply (Sensorless water supply mode)
P2.10	Carrier frequenc y sett-ing	0.5 ~ 15.0	0.1kHz	Type Confi rm	○	This value can be adju-sted to adj-ust motor noise
P2.12	Halt Mode select	0: Slow down and stop 1: Free parking	1	0	○	Frequency converter shutdown mode The alterna-tive is to deal with a drag Two and one drag is a free parking method
P2.13	The fa-ult is automati cally restored Position selection	0 ~ 5	1	3	○	Select 1 ~ 5 to open The fault is automatically reset Functionality . Runtime In case of failure, it will reset automatically after 10S, such as water shortage, line breaka-ge, high and low Pressure, burst pipe, external Fault, time arrived The fault is not affected by this func-tion code.
P2.15	Backup host	0.0 ~ 100.0	0.1%	80.0%	○	The standby host runs at

6、 Pump protection parameter group

FC	Function declarati on	Set the scope	Minimu m unit	Factor y va-lue	Ch an ge	Remarks
P 4.00	Water shortage protectio n funct-ion	0 ~ 2	1	2	○	0: Off 1: Start, ju-dge by frequ-ency and cur-rent 2: Turn on and let the water out The pressure of the mouth is judged
P 4.01	Water shortage fault Detection threshold	0.0 Bar ~ P0.00	0.1 Bar	0.5 Bar	○	When the fee-dback pressure is less than This setting value is used to determine whether there is water sho-rtage.
P 4.02	Excessive low water level protectio n Frequency of dete-ction	0.00Hz~ upper limit frequ-ency P2.07	0.00Hz	48.00 Hz	○	Determine wh-ether there is a shortage of water Compare frequ-encies, when in motion The frequency of the carrier is greater than this fr-equency When the rate is high, start judging the lack of water.
P 4.03	Excessive low water level protectio n Test time	0.0s ~ 200.0s	0.1s	60.0s	○	Meet the water shortage condi-tions, After this time, the wa-ter shortage fault is rep-orted.
P 4.04	Excessive low water level protectio n Detect the per-centage of curr-ent	0.0% ~ 100.0%	0.1%	40.0%	○	It is only valid when P 4.00 = 1, and the percentage of the rated current of the motor. When the running current is less than this current, it is judged as wa-ter shortage.
P 4.05	Water conservat ion is self-preserved Motion restart delay	0min ~ 9999 min	1min	15min	○	Set to 0: Use P4.07 and P 4.08 to reset the water sh-ortage fault. Set to non-0: the time for automatic re-set after the system detects water shorta-ge.
P 4.06	Water conservat ion is self-preserved Number of dynamic repositi ons	0 ~ 9999	1	100	○	After the wa-ter shortage fault, after P 4.05 time, the inverter is automatic Reset operat-ion, reset

8、 Protection and fault parameter groups

FC	Function declaration	Set the scope	Min i mum unit	Factory value	Change	Re ma rk s
P 6.00	Motor ove-rload Protection options	0: Prohi-bited 1: AI-lowed	1	1	○	0: No pr-otection 1: Prote-ction
P 6.01	Motor ove-rload Protect the gain	0.20~10.00	0.01	1 . 00	○	The motor overload protection is reverse Timeline
P 6.02	Motor ove-rload Warning coefficient	50% ~ 100%	1%	80%	○	The refe-rence va-lue of this value is the motor ov-erload current
P 6.08	Enter phase loss prot-ection	0: Prohi-bited 1: AI-lowed	1	1	○	Select whether to input a missing value The situ-ation is protected
P 6.09	Output ph-ase loss protection	0: Prohi-bited 1: AI-lowed	1	1	○	Select whether to output a defect The situ-ation is protected

9、 Terminal parameter group

FC	Function declaration	Set the scope	Min i mum unit	Factory value	Change	Remarks
P 7.00	X1 Input terminal function selection	0.1、2、7、11、12、13、18	Not have	1	●	0: No func-tion 1: Forward operation (FWD) 2: Reverse operation (REV) 7: Fault reset 11: Water shortage protection is always open input Pump 12:1 is faulty Pump 13:2 is faulty 18: Emerge-ncy water shortage manual aut-omatic swi-tch Note: The function data not drag the motor (For Prohibit=0, the frequency is not set)
P 7.01	X2 Input terminal function selection			11	●	
P 7.02	X3 terminal s FS			2	●	
P 7.08	Relay TA/TB/ TC output function Select	0、1、2、3、4	1	1	●	0: No output 1: Motor drag 2: Fault Functions

12、 Fault record parameter group

FC	Function declarat-ion	FC	Function declaration
E0.00	The most recent type of failure	E0.01	Frequency of the most recent failure
E0.02	The last time there was a fault, the current was	E0.03	Bus voltage at last failure
E0.04	The status of the input terminal is shown in the last failure	E0.05	Output on last failure Terminal status
E0.06	Status of the inv-erter during last failure	E0.07	Time of last failure (power on)
E0.08	Time (of operation) of last failure	E0 ~ E2 before 3 times Failure logging	

13. Common fault codes and countermeasures

Fault code	Fault type	Possible causes of failure	The way to deal with a situation
E002	Accelerate the operation over current	1. It's going too fast 2. The voltage of the grid is low 3. The power of the frequency converter is too small	1. Increase accele-ration time 2. Check the input power supply 3. Select a freque-ncy converter with a higher power
E003	Slow down to run over current	1. The speed was too slow 2 The power of the frequency converter is too small	1. Increase the de-celeration time 2 Increase the power of the frequency converter
E005	Accelerate the operation over voltage	1. The input volt-age is abnormal 2. After a sudden power failure, the motor in rotation is restarted	1. Check the input power supply 2. Avoid shutting down and restarting
E006	Slow down to avoid overvolt-age	1. The speed was too slow 2. The load inertia is large 3. The input volt-age is abnormal	1. Increase the de-celeration time 2. Increase the en-ergy consumption braking component 3. Check the input power supply
E009	Busbar under voltage	1. The voltage of the grid is low	1. Check the power input to the grid
E010	Frequency conv-erter overload	1. It's going too fast 2. Restart the mo-tor in rotation 3. The voltage of the grid is too low 4. The load is too large	1. Increase accele-ration time 2. Avoid shutting down and restarting 3. Check the grid voltage 4. Choose a more powerful inverter
E011	Motor overload	1. The voltage of the grid is too low 2. The rated curr-ent of the motor is not set correctly 3. Motor blockage or load sudden ch-ange is too large 4. Big horse and small car	1. Check the grid voltage 2. Reset the motor rated current 3. Check the load and adjust the tor-que increase 4. Choose the right motor
E012	Phase is missing on the input side	Enter R, S, T to have a missing ph-ase	1. Check the input power supply 2. Check the assem-bly line
E013	Phase loss on the output side	U, V, W phase mis-sing output (or load three-phase serious asymmetry)	1. Check the output wiring 2. Check motors and cables
E014	Module overhea-ting	1. Instantaneous overcurrent in the frequency converter 2. Output three-phase short circuit between phases or ground 3. Air duct block-age or fan damage 4. The ambient te-perature is too	1. See the flow co-untermeasure 2. Redraw the wiring 3. Open the air duct or replace the fan 4. Lower ambient temperature 5. Check and recon-nect 6. Seek services

	Standby frequency					a constant speed, for example: The maximum frequency is 50.00Hz, then the standby frequency is 40.00Hz。
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5、PID and sleep parameter group

FC	Function declaration	Set the scope	Minimum unit	Factory value	Change	Remarks
P 3.05	PID gives the source selection		1	0	○	0: The keyboard is given 1: AI1 given 2: AI2 given
P 3.07	PID feedback is disconnected Test time	0.0s ~ 100.0s	0.1s	30.0s	○	When the PID feedback value is still 0 after the detection time has elapsed, the feedback fault is reported. This function is invalid when set to 0.
P 3.09	PID wake-up detection delay	0.0s ~ 100.0s	0.1s	3.0s	○	PID wake-up detection delay
P 3.12	PID The sleep maintenance frequency	0.00Hz ~ P3.13	0.01Hz	20.00Hz	○	The PID runs at the sleep maintenance frequency. After the sleep maintenance time, the PID enters the sleep state
P 3.13	Sleep detection frequency	P3.12-Upper frequency	0.01Hz	25.00Hz	○	The system determines the hibernation bar The frequency with which the item is satisfied.
P 3.15	Pressure holding test Periodic intervals	0.0s ~ 120.0s	0.1s	60.0s	○	Every time this test cycle is completed Test the pressure holding state
P 3.18	PID feedback break line detection value	0.00V ~ 1.00V	0.01V	0.20V	○	Feedback disconnects the detection valve

						times are limited by this parameter, and reset is reached After a certain number of times, the water shortage fault cannot be automatically cleared, and the fault should be reset manually by pressing REST. Setting it to 9999 can reset the water shortage fault infinitely.
P 4.07	Check the incoming water pressure	0.0 Bar ~ P0.00	0.1 Bar	1.0 Bar	○	If the system reports water shortage fault (E027), the inverter detects the pressure after water comes in Greater than or equal to set incoming water Test pressure and time Greater than the water inflow detection time
P 4.08	Water arrival test time	0.0s ~ 100.0s	0.1s	20.0s	○	After that, the system automatically resets the E 027 fault. It is suitable for the inlet with pressure The pressurization system. This pressure Value is the outlet pressure value.

7、Motor parameter group

FC	Function declaration	Set the scope	Minimum unit	Factory value	Change	Remarks
P 5.01	Rated power of motor	0.1kW ~ 400.0kW	0.1kW	The model is determined	●	Set according to the motor nameplate
P 5.02	Rated voltage of motor	1 V ~ 440 V	1V	The model is determined	●	Set according to the motor nameplate
P 5.03	Rated motor current	0.01A ~ 655.35A (<= 55 kW) 0.1A ~ 6553.5A (> 55 kW)	0.01A/ 0.1A	The model is determined	●	Set according to the motor nameplate

						c_0
P 7.09	Relay PA/PC output function Select		1	2	●	(used for industrial frequency pump control) are prohibited from being set unless the function code is listed

10、Agent parameter group

FC	Function declaration	Set the scope	Unit	Factory value	Modification level	Remarks
Pd. 00	User password	0000 ~ 9999	Not have	0000	○	User password
Pd. 01	Parameter is restored to factory value	0 ~ 2	Not have	0	●	0: No operation 1: Restore factory value 2: The fault record is cleared
Pd. 02	Lock the parameters	0 ~ 1	Not have	0	○	0: Unlock 1: Lock

11、Monitoring parameter group

FC	Name	Unit
L0.00	Running frequency (Hz)	0.01Hz
L0.01	Set frequency (Hz)	0.01Hz
L0.02	Busbar voltage (V)	0.1V
L0.03	Output voltage (V)	1V
L0.04	Output (A)	0.01A (>55Kw, 0.1A)
L0.05	Output power (kW)	0.1kW
L0.06	Output torque (%)	0.1%
L0.07	DI input mode	1
L0.08	D0 output state	1
L0.09	AI1 Voltage (V)	0.01V
L0.10	AI2 voltage (V)	0.01V
L0.11	Cumulative on-line time	1H
L0.12	Cumulative running time	1H
L0.13	Total power consumption	1 linear measure
L0.14	Load speed (RPM)	1RPM
L0.15	PID Settings (Bar)	0.1 Bar
L0.16	PID feedback (Bar)	0.1 Bar

		high 5. The wiring or plug of the control panel is loose 6. The power circuit is not normal 7. Board is abnormal	
E015	External faults	External fault input terminal action	1 Check external device input
E016	Communication failure	1. The baud rate is not set properly 2. Communication error using serial communication 3. The communication was intermittently interrupted	1. Set the appropriate baud rate 2. Press RUN/STOP, key reset, seek service 3. Check the communication interface wiring
E017	Connect the power relay Hitch	1. The relay is not engaged	1. Replace the power on relay or seek technical support
E023	Ground short circuit fault	1. Check if the motor is short circuit to ground	1. Replace the cable or motor 2. Seek services
E024	Feedback line fault	1. Sensor is disconnected or has poor contact 2. The disconnection detection time is too short 3. Sensor damage or no feedback signal from the system	1. Check sensor installation and wiring 2. Adjust the wire break detection time 3. Replace the sensor
E027	Water shortage alarm	1. Abnormal water pressure / water level. 2. The sensor is disconnected or the contact is poor, and the system has no feedback signal. 3. The water shortage protection detection time is too short 4. The frequency of water shortage protection detection is too low 5. The water shortage protection detects the current as too high	1. Check whether the water inlet pressure of the pump is abnormal 2. Check sensor installation and wiring 3. Check the relevant parameter Settings
E028	High water pressure alarm	1. The sensor feedback signal is abnormal 2. The high alarm value is too low	1. Connect the detection sensor 2. Set relevant parameters for detection
E050	Multi-split Communication error	1. Multi-serial communication is abnormal 2. The network address of the multi-split unit is duplicated	1. Re-energize 2. Check the CAN networking address Settings 3. Seek services
E100 E110	The keyboard communication is faulty	1. Check that the keyboard communication wiring is normal 2. Check that the control panel is normal 3. Check that the keyboard is working properly	1. Replace the keyboard cable 2. Replace the control panel or keyboard 3. Seek services

p 5.04	Rated fr- equency of motor	0.01Hz~ maximum frequency	0.01Hz	The model is deter- mi ned	●	Set acco- rding to the motor nameplate
p 5.05	Rated sp- eed of motor	1rpm ~ 36000rpm	1rpm	The model is deter- mi ned	●	Set acco- rding to the motor nameplate